

<b>SEMESTER</b> <i>Eighth</i>	<b>DEPARTMENT</b> <i>Power Engineering</i>	<b>COURSE TITLE</b> <i>Microcontrollers</i>
<b>COURSE CODE</b> <i>EC807</i>	<b>HOURS:</b> 3 <b>UNITS:</b> 3	<b>COURSE SPECIFICATIONS</b> <i>Theoretical Content</i>
<b>1. Computer Systems:</b> <ul style="list-style-type: none"> <li>➤ PC systems.</li> <li>➤ Microprocessor systems.</li> <li>➤ Microcontroller systems.</li> <li>➤ Basic Architecture of MCU.</li> <li>➤ Von Neumann and Harvard architectures</li> <li>➤ CISC and RISC architectures</li> </ul>		
<b>2. Information Coding:</b> <ul style="list-style-type: none"> <li>➤ Overview in number systems.</li> <li>➤ Levels of programming languages.</li> <li>➤ Structure of assembly language.</li> </ul>		
<b>3. PIC Microcontroller:</b> <ul style="list-style-type: none"> <li>➤ PIC microcontroller families.</li> <li>➤ The arithmetic and logic unit (ALU) and the Working register in PIC MCU.</li> <li>➤ Machine cycles and execution of instructions.</li> <li>➤ Pipelining for instruction execution.</li> <li>➤ Oscillators.</li> <li>➤ Watchdog.</li> </ul>		
<b>4. Memory in PIC MCU:</b> <ul style="list-style-type: none"> <li>➤ Logic organization of memory.</li> <li>➤ Types of memory.</li> <li>➤ Memory in Medium- End PIC MCU:                             <ul style="list-style-type: none"> <li>• Program memory.</li> <li>• RAM data memory</li> </ul> </li> </ul>		

**5. Instruction Set in Medium-End PIC Microcontrollers (from PIC16F628 datasheet):**

- Data transfer instructions .
- Arithmetic and logic instructions.
- Control transfer instructions: including subroutine ,calls and returns.
- Bit manipulation instructions.
- Arithmetic operators.

**6. Parallel Input/ Output in PIC MCU:**

- Basic concepts : peripheral , port..etc.
- Data transfer techniques
- Input/Output Techniques .
- Parallel Ports in Medium-End PIC Microcontrollers : (Port A – G and parallel slave port).
- Connection of commonly used peripherals : (Switches, LEDs, 7 segment display..etc).

**7. Timers and Counters:**

- Timers and counters in PIC MCU.
- Types of counters.
- Timer modules:
  - Timer0 module.
  - Timer1 module.
  - Timer2 module.
- The CCP module: capture mode; compare mode; and PWM mode.

**8. Interrupts:**

- General structure of an interrupt service subroutine.
- Interrupt sources and associated registers in PIC MCU.
- Interrupt service subroutine structure in PIC MCU.
- An example of interrupt Applications: real time clock.

**9. Serial Input and Output:**

- Introduction to serial data transmission.
- Asynchronous communication.
- Synchronous communication.

**References:**

1. Fernando E. Valdes-Perez, Ramon Pallas-Areny, *Microcontrollers ,Fundamentals and Applications with PIC*, CSC Press.
2. PIC16F628 datasheet.
3. [www.microchip.com](http://www.microchip.com)
4. MPLAB IDE (free versions can be downloaded from Microchip)